Informal Seminar on Stanley-Reisner Theory, UMN, Fall 2002 17 October 2002

## Introduction and motivation for Stanley-Reisner rings, I

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## 1. Definitions

**Definition 1.** Let V be a finite set of vertices. An abstract simplicial complex  $\Delta$  on V is a subset of the power set  $2^V$  which is closed under inclusion, that is,

$$F \in \Delta, \ G \subset F \implies G \in \Delta.$$

The elements of  $\Delta$  are called *faces*. The dimension of a face, dim F, is defined as |F|-1.

We can often represent  $\Delta$  pictorially. For instance, if  $V = \{a, b, c, d\}$  and  $\Delta$  is the abstract simplicial complex (1)  $\Delta = \{\emptyset, a, b, c, d, ab, bc, cd\}$ 

(abbreviating the face  $\{a\}$  by a,  $\{a,b\}$  by ab, etc.), then the corresponding figure is



One can think of a, b, c, d as orthonormal basis vectors in |V|-space, so that the face ab (which has dimension 1) represents the affine span of the vectors a, b (which is a line segment), etc.

Fix a field k, and let

$$S = \mathbf{k}[x_v : v \in V],$$

the (commutative) polynomial ring in variables corresponding to the vertices.

**Definition 2.** The Stanley-Reisner ideal of  $\Delta$  is

$$I_{\Delta} := \left(\prod_{j=1}^r x_{v_{i_j}} : \{v_{i_1}, \dots, v_{i_r}\} \not\in \Delta\right).$$

Note that  $I_{\Delta}$  is a monomial ideal (that is, it is generated by monomials) and that the generators are squarefree (they are not divisible by the square of any variable). A minimal set of generators is given by the minimal nonfaces of  $\Delta$ .

**Definition 3.** The Stanley-Reisner ring (or face ring) of  $\Delta$  is

$$\mathbf{k}[\Delta] := S/I_{\Delta}.$$

Note that the set of monomials

$$\left\{x_{v_1}^{e_1} \dots x_{v_r}^{e_r} : \left\{v_1, \dots, v_r\right\} \in \Delta, e_1, \dots, e_r > 0\right\}$$

is a basis for  $\mathbf{k}[\Delta]$  as a **k**-vector space. In particular,  $\mathbf{k}[\Delta]$  is a graded ring.

For example, if  $\Delta$  is the simplicial complex given in (1), then

$$I_{\Delta} = (ac, ad, bd)$$

(the minimal nonfaces of  $\Delta$ ) and  $\mathbf{k}[\Delta]$  is the k-linear span of

$$\left\{
\begin{array}{l}
1, a, a^2, a^3, \dots, & ab, a^2b, ab^2, \dots, \\
1, b, b^2, b^3, \dots, & bc, b^2c, bc^2, \dots, \\
1, c, c^2, c^3, \dots, & cd, c^2d, cd^2, \dots, \\
1, d, d^2, d^3, \dots
\end{array}
\right\}.$$

This construction actually gives a bijection between simplicial complexes on V and ideals of S generated by squarefree monomials. The simplicial complex corresponding to such an ideal is its Stanley-Reisner complex.

## 2. Motivations

1. In algebraic geometry, one wants to study rings of the form R = S/I, where S is a polynomial ring over a field **k** and I is an ideal of S. That is, R is the coordinate ring of the affine algebraic variety defined by I. To study R using Stanley-Reisner rings, we may proceed as follows:

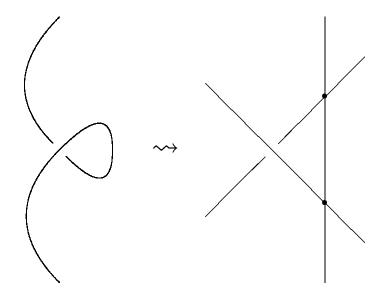
First, "deform" I as follows. Fix some monomial order < on S and compute the *initial ideal*  $\operatorname{in}_{<}(I) \subset S$  (this is equivalent to computing a Gröbner basis of I). By definition,  $\operatorname{in}_{<}(I)$  is generated by monomials, However, the generators need not be squarefree, so a second step, *polarization*, may be required. The idea of this step is to get rid of high powers of variables by the following trick: if one of the generators of  $\operatorname{in}_{<}(I)$  is, say,  $x^2$ , then we adjoin a new variable x', replace  $x^2$  with xx', and mod out by x - x'. The result is a squarefree monomial ideal of some polynomial ring  $S' \supset S$ , which we may regard as the Stanley-Reisner ideal  $I_{\Delta}$  of a simplicial complex  $\Delta$  on the variables of S'. The ideal  $\operatorname{in}_{<}(I)$  and its polarization are  $\operatorname{very}$  closely related, so we don't have to worry too much about this second step.

The passage from I to  $\operatorname{in}_{<}(I)$  does not preserve all structure, but it is pretty good (in the language of algebraic geometry, it is a flat deformation). Lots of geometric/ring invariants of R are closely related—often equal—to those of  $\mathbf{k}[\Delta] = S'/I_{\Delta}$ . For instance, the dimension, degree and Hilbert series of R are the same as for  $\mathbf{k}[\Delta]$ , and these can be computed combinatorially from  $\Delta$ . In addition, some homological-type properties, such as Cohen-Macaulayness, can only get worse–e.g., if  $\mathbf{k}[\Delta]$  is Cohen-Macaulay then so is R. (For an example, see the scribe's Ph.D. thesis.)

Here's an elementary example. Let  $S = \mathbf{k}[a, b, c, d]$ ,  $I = (ac - b^2, bd - c^2, ad - bc)$ , and R = S/I. (In fact, Proj(R) is the twisted cubic, the image of the degree-3 Veronese embedding  $\mathbb{P}^1 \to \mathbb{P}^3$  mapping [s:t] to  $[s^3:s^2t:st^2:t^3]$  in homogeneous coordinates.) The given generators of I form a Gröbner basis with respect to lexicographic order on the monomials of S, with a < b < c < d, so the initial ideal is

$$\operatorname{in}_{<}(I) = (ac, bd, ad),$$

the Stanley-Reisner ideal of the simplicial complex  $\Delta$  given in (1). Geometrically, the twisted cubic is being "flattened out":



We compute the dimension, degree and Hilbert series of the twisted cubic using  $\mathbf{k}[\Delta]$ .

Fact:  $\dim \mathbf{k}[\Delta] = 1 + \dim \Delta = 1 + \max \{\dim F : F \in \Delta\}.$ 

In this case, the largest faces have dimension 1, so dim R=2. It seems as though R should have dimension 1, but it is really the affine coordinate ring of the cone over the twisted cubic, so dim R=2 makes sense.

**Fact:** deg  $\mathbf{k}[\Delta]$  = number of facets (maximal faces) of  $\Delta$ .

Here, that number is 3.

Now for the Hilbert series. By definition, this is

$$\operatorname{Hilb}(\mathbf{k}[\Delta],t) := \sum_{m \geq 0} \left( \dim_{\mathbf{k}}(\mathbf{k}[\Delta])_m \right) t^m$$

where  $(\mathbf{k}[\Delta])_m$  denotes the *m*th graded piece of  $\mathbf{k}[\Delta]$  (that is, the **k**-linear span of the monomials of degree m. We have already written down a monomial basis (2) for  $\mathbf{k}[\Delta]$ . The minimal elements of the basis correspond to faces of  $\Delta$ , and we have

$$\begin{aligned} \operatorname{Hilb}(\mathbf{k}[\Delta], t) &= 1 + 4\left(\frac{t}{1-t}\right) + 3\left(\frac{t^2}{(1-t)^2}\right) \\ &= \frac{1+2t}{(1-t)^2}. \end{aligned}$$

The dimension and degree can be extracted from the Hilbert series: the dimension is the order of the pole at t=1 (here 2), and the degree is the sum of the coefficients in the numerator (here 3). The Hilbert series has the following combinatorial interpretation in terms of  $\Delta$ .

**Definition 4.** The f-vector of  $\Delta$  is

$$f(\Delta) = (f_{-1}, f_0, f_1, \dots, f_{\dim \Delta}),$$

where  $f_i$  is the number of i-dimensional faces. (So  $f_{-1} = 1$ , since  $\emptyset$  is the unique face of dimension -1, and  $f_0$  is the number of vertices.)

**Definition 5.** The h-vector of  $\Delta$  is

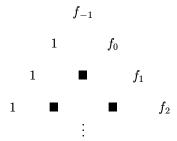
$$h(\Delta) = (h_0, h_1, \dots, h_{\dim \Delta + 1}),$$

where  $h_i$  is defined as follows. You can use the formula

$$\sum_{i} h_{i} t^{i} = \sum_{i=0}^{\dim \Delta + 1} f_{i-1} t^{i} (1-t)^{\dim \Delta - i + 1}$$

(Bruns and Herzog, Lemma 5.1.8).

A more fun way to compute the h-vector is as follows. First, draw a triangle with the coefficients of the f-vector down the rightmost diagonal, and 1's down the leftmost diagonal:



Then, fill in the  $\blacksquare$ 's down to the row below  $f_{\dim \Delta}$  as though you were constructing Pascal's triangle—but subtracting instead of adding. That is, replace each  $\blacksquare$  with the number to the northeast minus the number to the northwest. The bottom row will be the h-vector.

For example, for the complex  $\Delta$  we have been working with, we start with

Filling in the boxes, we get

The numbers below the line form the h-vector, in this case (1,2,0). The trailing 0's are frequently dropped, so we would write  $h(\Delta) = (1,2)$ .

Now back to the Hilbert series. The connection is the following:

$$\begin{aligned} \operatorname{Hilb}(\mathbf{k}[\Delta],t) &:= & \sum_{m\geq 0} \left( \dim_{\mathbf{k}}(\mathbf{k}[\Delta])_m \right) t^m \\ &= & \sum_{i\geq 0} f_i(\Delta) \left( \frac{t}{1-t} \right)^{i+1} \\ &= & \frac{\sum_{i=0}^{\dim \Delta + 1} h_i t^i}{(1-t)^{\dim \Delta + 1}}. \end{aligned}$$